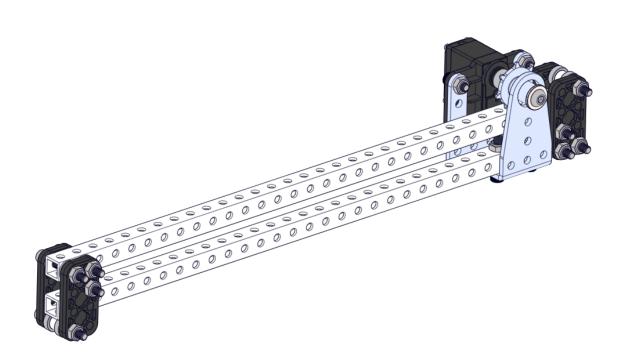


(am-5519) Assembly Guide



Revision #	Date	Author	Purpose
0	9/16/2024	Ethan Scime	Original Document

P. Yeung	9/18/2024			
Reviewer Name	Date Reviewed			

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Parts & Tools —

Recommended Tools List

Component	Part #	QTY	Photo
5/32" Ball End Hex Driver	am-2751	1	Officeron and the second secon
2.5mm Hex Driver, L-Shaped	am-1288	1	
3/8 Combination Wrench	am-4961	1	3 45 45 0% ATTES 474 O

Parts List

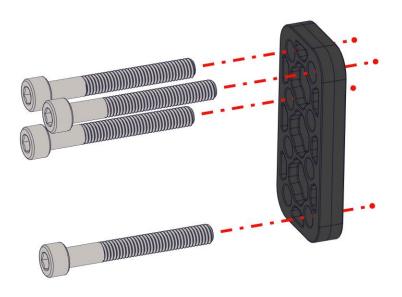
Component	Part #	QTY	Photo
Cog Drive Servo Bracket	am-5041	1	
0.5" 10-32 Socket Head Cap Screw	am-1002	2	
1" 10-32 Socket Head Cap Screw	am-1056	2	
1.5" 10-32 Socket Head Cap Screw	am-1014	8	
10-32 Nylock Jam Nut	am-1063	12	
ROBITS 2x4 Plate Gusset	am-5006_2x4	4	
#10 Washer	am-1026	8	
5mm Unflanged Bearing	am-4724	8	

Component	Part #	QTY	Photo
ROBITS Bushing	am-5021	1	
7T Cog	am-5472	1	
1.25" 10-32 Socket Head Cap Screw	am-1041	2	No. of Contract of
0.125" #10 Screw Spacer	am-1732	2	
ROBITS Motor Mount, 80T-100T	am-5017	1	
0.5" Shaft Spacer	am-1699	1	
8mm M3 Socket Head Cap Screw	am-1500	3	W. Halland
1/4" #10 Nylon Screw Spacer	am-1700	6	

Assembly

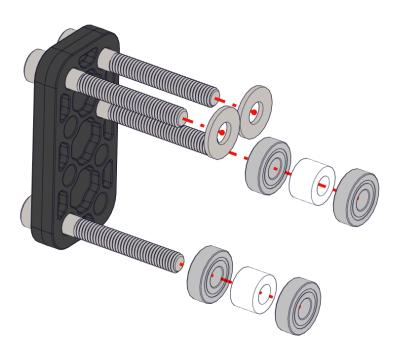
Step 1

Insert [4] 1.5" 10-32 Screws (am-1014) through the ROBITS 2x4 Plate Gusset (am-5006_2x4) as shown.

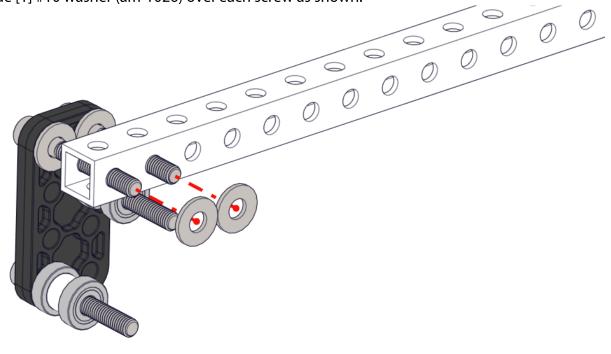


Step 2

Slip a #10 washer (am-1026) over each of the top [2] screws as shown. Place a 5mm bearing (am-4724), a 1/4" screw spacer, and then a second 5mm bearing over the remaining screws as shown.

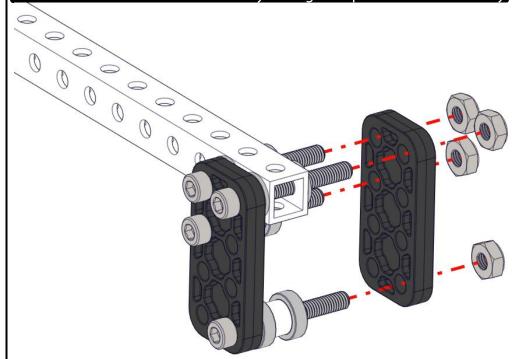


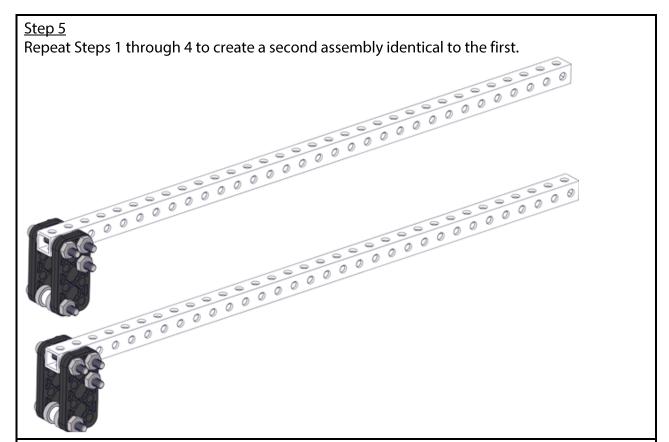
Slip a ROBITS tube (not included, am-5001-1400 shown) over both of the top screws, then slide [1] #10 washer (am-1026) over each screw as shown.



Step 4

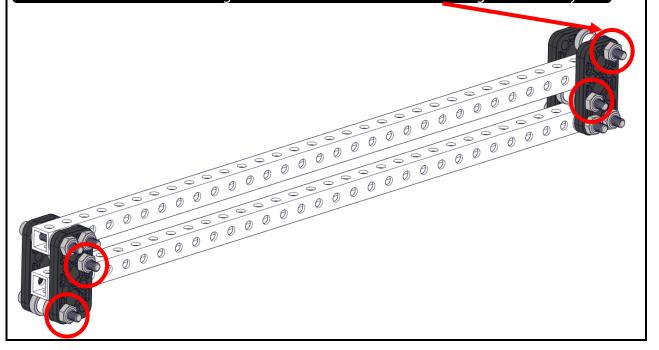
Cover the assembly with another ROBITS 2x4 Plate Gusset (am-5006_2x4) and secure it in place using [4] 10-32 Nylock nuts, [1] for each screw. Do not overtighten! A 0.5x0.5 ROBITS tube should be able to slide smoothly through the pocket in the assembly.





Rotate one assembly and insert the two into each other as shown. Ensure the assemblies freely glide through each other when completely assembled.

If the assemblies do not move freely, loosen the screws constraining the bearings until the tube movement is smooth. Retighten them until the screw can no longer slide axially.

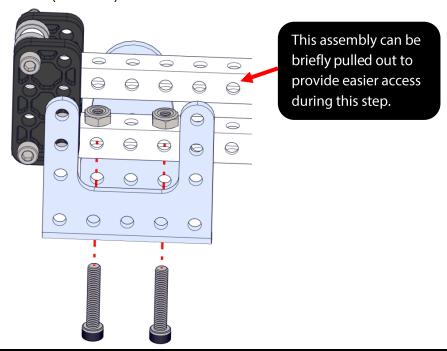




If you'd like to use a NeveRest motor to power your Cog drive, jump to Step 11. Otherwise, continue with Step 7.

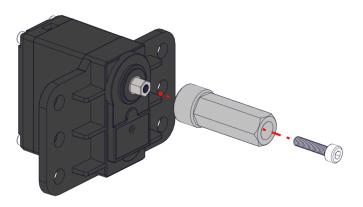
Step 7

Attach a Cog Drive Servo Bracket (am-5041) to one of the assemblies using [2] 1" 10-32 Screws (am-1056) and [2] #10 Nylock Nuts (am-1063) where shown.

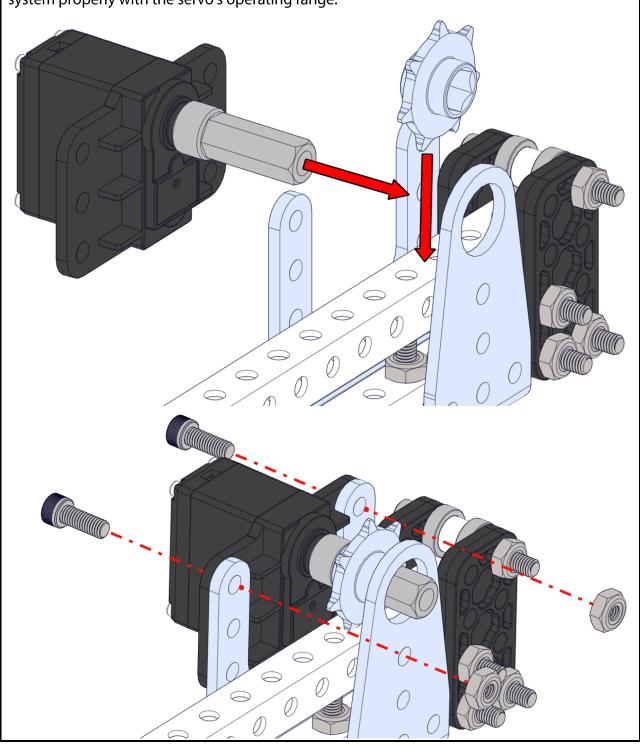


Step 8

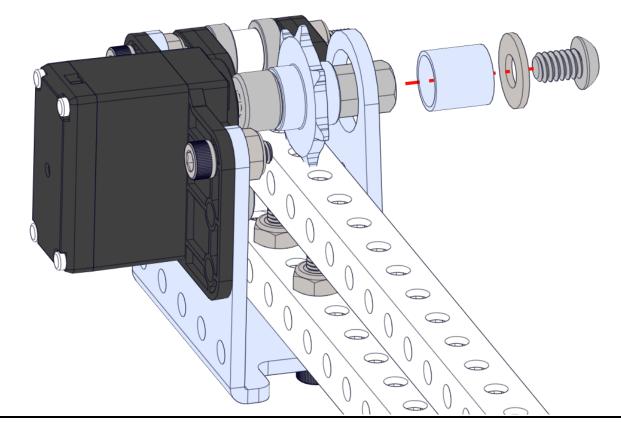
Secure a Servo Adapter to a Servo using [1] M3 screw included with the adapter.



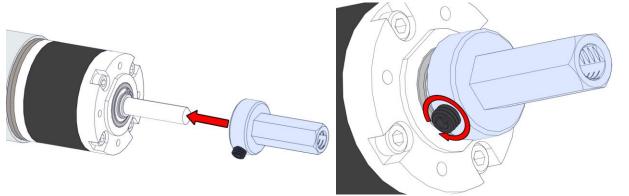
Place the 7 Tooth Cog (am-5472) so that its teeth insert into the holes on one of the assemblies. Insert the Servo through it, then secure the servo in place with [2] 0.5" 10-32 screws (am-1002) and [2] 10-32 nuts (am-1063). You may need to repeat this step to align the system properly with the servo's operating range.



Slip a 0.5" Shaft Spacer (am-1699) over the end of the Servo shaft and secure it in place with the 1/4" washer and screw included with the Servo adapter. The servo-driven Cog Drive is now COMPLETE. Do not continue to Step 11.

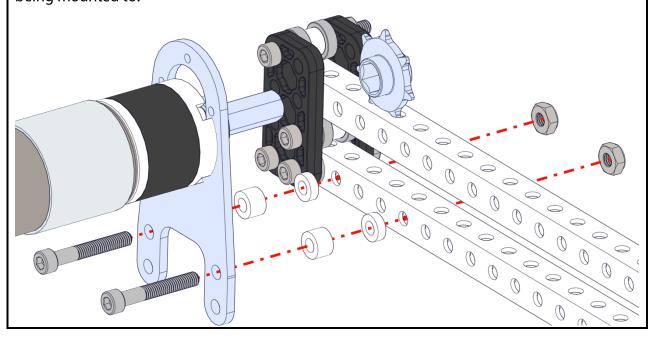


<u>Step 11</u>
Attach the NeveRest to 3/8" hex adapter by slipping it over the shaft and tightening the set screw as shown.



Step 12
Attach the NeveRest motor to a ROBITS Motor Mount, 80T-100T (am-5017) using [3] 8mm M3 screws (am-1500)

With the 7 Tooth Cog (am-5472) ready in place through the holes in one of the ROBITS tubes, attach the motor/motor mount with [2] 1.25" 10-32 screws and [2] 10-32 nuts. Use [1] 0.25" Screw Spacer and [1] 0.125" Screw Spacer per screw to space motor off the ROBITS tube it is being mounted to.



<u>Step 14</u>

Slip a 0.5" Shaft Spacer (am-1699) over the end of the Servo shaft and secure it in place with the 1/4" washer and screw included with the shaft adapter. The motor-driven Cog Drive is now COMPLETE.

